# CONTROL ENGINEERING TRAINER

# Model Number: GOTT-CET-X232





### **DESCRIPTION**

This Control Engineering Trainer is designed to meet the future automation training program. In this era of automation, control engineering is a vital prerequisite for modern mechanisms for such system required a detailed knowledge of how a controlled systems work.

### **FEATURES**

- **PC Based Control**
- Can link to any PCs for simple drive control system
- Easily and Portable
- Control commands and motion commands
- User friendly programming language
- Learn programming environment and debugging functions.

#### **ACCESSORIES**

- Industry-best textbooks
- Workbooks and hands-on exercises
- Comprehensive Assessments Tool
- A set of Computer
- PID Software

### **GENERAL SPECIFICATION**

- Inverter
- Switching mode power supply
- AC Motor
- LED Lighting (Brightness Controller)
- Temperature Module
- Lab View Software
- **Aluminium Casing**
- **Power Cord**
- Software Installation Disc
- Instruction Manual

### 16-CH 12-BIT ADVANCED MULTI-FUNCTION DAS CARD

### **Features**

- 32-bit PCI Bus with Bus-mastering DMA
- 12-bit analog input resolution
- 16 single-ended or 8 differential analog input
- On-board A/D FIFO memory
- Auto-scanning channel selection
- Up to 110 KHz A/D sampling rates
- Programmable gain of x0.5, x1, x2, x4, x8
- Bipolar or unipolar input signals
- Three A/D trigger modes: software trigger, programmable pacer trigger, and external pulse trigger
- 16-bit digital input and 16-bit digital output
- Two 12-bit monolithic multiplying analog output channels
- 3 independent programmable 16-bit down counters
- Compact, half-size PCB
- 37-pin D-type connector





### ATV312H075M2 AC DRIVE

### **Features**

Motor Power Rating: 0.75kW

Input Voltage: 208/230VAC

Marketing Trade Name: Altivar 312

Output Voltage: Maximum Output Voltage Equal To Input Voltage

Input Phase: 1-Phase Frame Size: Size 3

Horsepower Rating: 1HP

Type: ATV312

Output Phase: 3-Phase Conformal Coating: No Degree Of Protection: IP20

Ampere Rating: 1.5A

Embedded Communication: Modbus And CANopen

Integrated EMC Filter: Class A

Enclose Rating: Open

Application : Constant Torque





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#### SOFTWARE EXPERIMENT

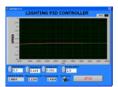
### **Open Loop Control**

- · Speed setting for motor
- · Graph reading for speed and time
- Voltage driver input
- Average slot found function



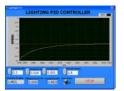
# **Closed Loop Control**

- Value setting for proportional (P), integration (I) and derivation (D)
- Voltage driver input
- Intensity reading and setting



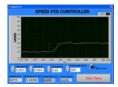
### **Lighting PID**

- · Value setting for proportional (P), integration (I) and derivation (D)
- Voltage driver input
- · Intensity reading and setting



### **Speed PID**

- Speed setting for motor
- Graph reading for speed and time
- · Voltage driver input
- Average slot found function
- · Manually configured value for motor



### **Manual Mode**

The manual mode of PID controller consists of:

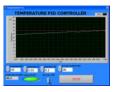
- Fan button
- SSR1 and SSR2 button
- Analogue Output (Motor Speed) button
- Analogue Output (Light Intensity) button
- Counter Input
- Temperature Value
- · Stop button



## **Temperature PID**

The below screen shows the temperature mode of PID controller:

- Type of input sensor (thermocouple, RTD) and temperature range
- Type of output required (electromechanical relay, SSR, analog output)
- Control algorithm needed (on/off, proportional, PID)
- Number and type of outputs (heat, cool, alarm, limit)



### **Fuzzy Logic**

The Controller Design Interface is a stand-alone with a user interface you can use to completely define all controller and expert system components and save all of the parameters of the defined controller to one controller data file



#### **EXPERIMENT TOPICS:**

- Open Loop Control
- Closed Loop Control
- Manual Mode
- Temperature PID
  - Sample of Setting the Temperature (Default Value)
  - Changing Value P
  - Changing Value I
  - Changing Value D
- Lighting PID
  - Sample of Setting the Temperature (Default Value)
  - Changing Value P
  - Changing Value I
  - Changing Value D
- Speed PID
  - Sample of Setting the Speed (Default Value)
  - Changing Value P
  - Changing Value I
  - Changing Value D
- **Fuzzy Logic**

#### Manuals:

- (1) All manuals are written in English
- (2) Model Answer
- (3) Teaching Manuals

### **General Terms:**

- (1) Accessories will be provided where applicable.
- (2) Manual & Training will be provided where applicable.
- (3) Design & specifications are subject to change without notice. (4) We reserve the right to discontinue the manufacturing of any product.

## Warranty: 2 Years

### **ORDERING INFORMATION:**

ITEM	MODEL NUMBER	CODE
CONTROL ENGINEERING TRAINER	GOTT-CET-X232	232-288