



DLQD-JXS1 Electro Pneumatic Manipulator Trainer

■ Overview

- The electro pneumatic manipulator trainer is composed of aluminum panel, belt conveyor, manipulator, pneumatic system and PLC signal switching module.
- The device simulates industrial working condition, it can handling and transfer the materials and parts. Test cylinder's position through various sensors, then handling by the manipulator model, convey the materials and parts by the conveyor belt module.

■ Technical Parameter

- Total dimension: 250 X 600 X 400mm
- Input power: DC24V

- Capacity: < 100VA