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## DLDS-1508 industrial robot application training system

Equipment overview
DLDS-1508 industrial robot application training system consist of training platform, spare parts store, four axis Berger Lahr mechanical handling unit, ring assembly inspection mechanism, ABB six joint industrial robot assembly sorting unit, visual detection device, finished product storehouse.

The main task of the device is based on MES management software, order demand, Berger Lahr robot grab the corresponding to red or yellow, blue button cap and other button assembly parts from the spare parts store. And the assembly part is placed in fixed position of ring assembly detecting mechanism. Then assembly structure detection is rotated 180 degrees, reach the assembly inspection station of robot with six degrees of freedom. robot with six degrees of freedom carring on the button assembly, after the completion of the assembly, the power supply mechanism send electricity to the button. The robot press the button, then through vision cameras to detect and judge the button's color and quality, the six degree of freedom robot according to the data of the vision camera for classfication. Thereby it is carried on the finished product store.

Technical parameter
1 input power: single phase 3 -line $\mathrm{AC} 220 \mathrm{~V} \pm 10 \% 50 \mathrm{HZ}$.
2 Working environment: temperature $-10^{\circ} \mathrm{C}-+40^{\circ} \mathrm{C}$, relative humidity $<85 \%\left(25^{\circ} \mathrm{C}\right)$, no condensation of water droplets at the altitude $<4000 \mathrm{~m}$

3 output power:
(1) AC single phase $220 \mathrm{~V} \pm 10 \% 50 \mathrm{HZ}$; starting switch control output.
(2) DC regulated voltage power: $24 \mathrm{~V} / 5 \mathrm{~A}$.

4 Equipment dimension: $1900 * 900 * 1500 \mathrm{~mm}\left(\mathrm{~L}^{*} \mathrm{~W} * \mathrm{H}\right)$
5 Safety protection function: emergency stop button, leakage protection.
6 PLC: Siemens (optional model)
7 ABB six joint robot:
(1) robot model: IRB120-3/0.58.
(2) Maximum grab weight: 3KG.
(3) action semidiameter: 0.58 m .
(4) Repeated positioning accuracy: 0.01 mm .

8 Bergerlahr manipulator
(1) X axis stroke: 500 mm ;
(2) $Y$ axis stroke: 500 mm ;
(3) $Z$ axis stroke: 150 mm ;
(4) Rotation angle of rotating shaft: $180^{\circ}$.

